

Large Area Transport Simulations: Climbing the Mountain – Near Term Research Challenges

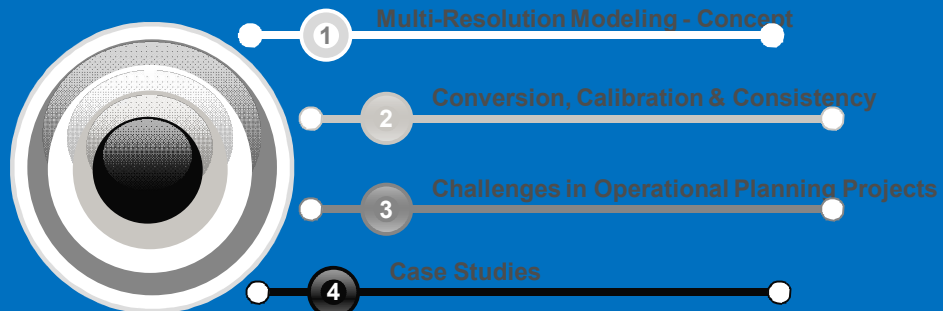
“Multi-Resolution Modeling: Incorporating
Dynamic Traffic Assignment into Operational
Planning Projects”

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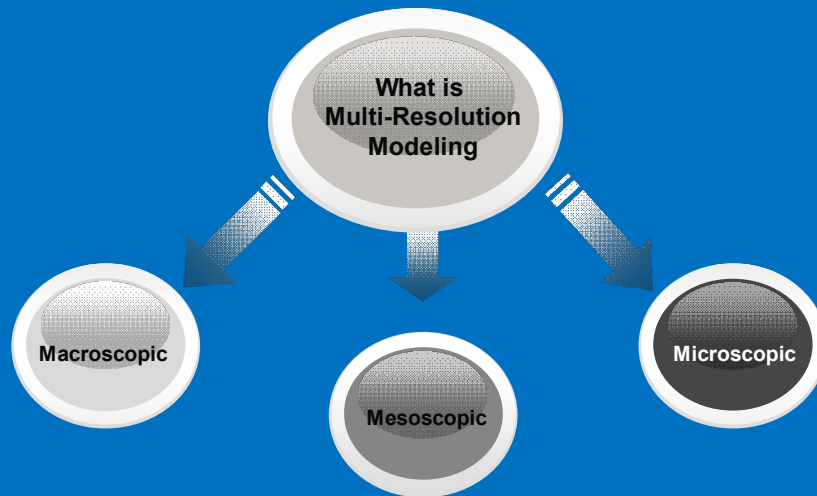
September 22, 2010



Outline



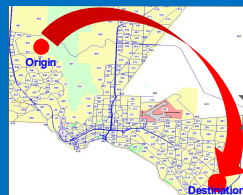
Multi-Resolution Modeling-Concept



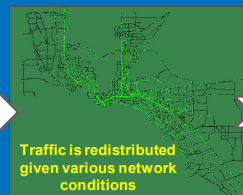
Integrating macro, meso and micro model to achieve a specific goal

Multi-Resolution Modeling-Concept

- Model integration takes the strengths of all models
 - TDM gives blueprint of network and provides O/D
 - DTA model provides region-wide estimation of traffic redistribution
 - Micro- local operational analysis



Regional Travel Demand Model



Simulation-Based DTA Model



Sub-area Microscopic Model

Multi-Resolution Modeling-Concept

- Why is multi-resolution modeling so important?
 - **Models are not mutually exclusive**
 - **They are complimentary to one another and can accomplish optimal modeling capabilities.**
 - **Retain the best characteristics**
 - Realistic representation of regional traffic
 - Detailed interactions
 - **Challenges remain in model translation and interface**
 - Calibration
 - Consistency

Multi-Resolution Modeling-Concept

Understanding what you
are trying to model



- Use DTA for travel demand modeling to understand the spatial and temporal distribution of traffic during peak periods
- Sub – area analysis for detailed operations studies

Which model resolution
integration suits situation
best?

Model Conversion Process

```
graph LR; A[Regional Travel Demand Model] --> B[Initial Network Conversion Meso Model]; B --> C[Calibration<br/>-OD<br/>-Traffic Model]; D[Field Data] --> C; C --> E[Run Dynamic Traffic Assignment]; E --> F[Sub-area]; F --> G[Conversion Tool]; G --> H[Micro-Model]; H --> I{Rerun DTA}; I -- Yes --> C; I -- No --> J[Detailed Analysis];
```

The flowchart illustrates the Model Conversion Process, starting with a Regional Travel Demand Model, which is converted into an Initial Network Conversion Meso Model. This model is then calibrated using Field Data and converted into a Micro-Model. The Micro-Model is used to run a Dynamic Traffic Assignment (DTA) simulation. If the simulation results are satisfactory (Yes), the process continues to the next step. If not (No), the process loops back to the Calibration step. The final output is a Detailed Analysis.

➤ Significant change to roadway configuration

➤ Certain corridor management strategies

Macro → Meso → Micro

Calibration

- Time-dependent OD
 - Minimize the deviation between simulated and actual screen line counts & speed profile
 - Iterative process
 - Program solves linearized quadratic minimization problem
 - Results in updated OD matrices

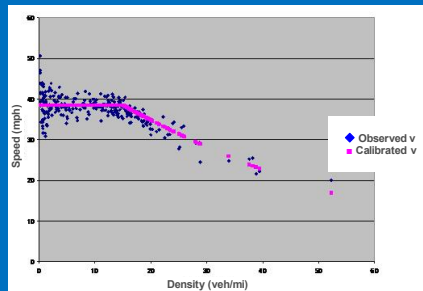
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graph TD; A[Traffic Network Traffic Flow Model Intersection Controls] --> C[Traffic Assignment/ Simulation]; B[Estimated Time-Dependent OD Matrices] --> C; C --> D[Assignment Results]; D --> E[Linear Optimization Model]; E --> F[Results]; F --> G[Optimized Affected, Time-Dependent OD Pairs]; G --> H[Update Demand]; H --> B;
```

The flowchart illustrates an iterative calibration process. It begins with two inputs: 'Traffic Network Traffic Flow Model Intersection Controls' and 'Estimated Time-Dependent OD Matrices'. These feed into 'Traffic Assignment/ Simulation', which produces 'Assignment Results'. These results are then used in a 'Linear Optimization Model' to generate 'Results'. These results are used to create 'Optimized Affected, Time-Dependent OD Pairs'. A feedback loop labeled 'Update Demand' connects these optimized pairs back to the 'Estimated Time-Dependent OD Matrices' input, completing the iterative cycle.

- Time-dependent OD
 - Minimize the deviation between simulated and actual screen line counts & speed profile
 - Iterative process
 - Program solves linearized quadratic minimization problem
 - Results in updated OD matrices

Calibration

- Traffic flow model
 - Traffic simulation in DynusT is based upon the Anisotropic Mesoscopic Simulation (AMS) model
 - Moves vehicle based upon speed-density (v-k) relationship
 - v-k relationship is derived from Greenshield's equation



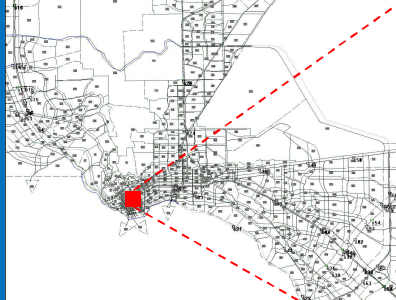
Consistency

- Network
 - Lane configuration
 - Geometric design
- Paths and flows
 - Verify same origin/destination paths
 - Verify number of vehicles generated
- Speed profile
 - Perform field data collection to determine speed and vehicle counts
 - Obtain v-k curve from simulation output
 - Calibrate models with field data

Challenges in Operational Planning

- How do you incorporate realistic traffic control into future year models?

DTA model



Input all existing signal control data into regional model

CITY OF EL PASO
ENGINEERING DEPARTMENT TRAFFIC DIVISION
TRAFFIC SIGNAL TIMING SHEET

LOCATION: COTTON & MYRTLE
SYSTEM ID: P 4 ADDRESS: 204

Signal Name	Phase 1		Phase 2		Phase 3		Phase 4		Phase 5		Phase 6		Phase 7		Phase 8		
	Left	Thru	Left	Thru	Left	Thru	Left	Thru	Left	Thru	Left	Thru	Left	Thru	Left	Thru	
Maximum 1	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30
Maximum 2	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30	30
Max Clearance	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4	4
Min Ped	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
Min Clearance	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10
Min Clearance	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10	10
Normal Phase Operation	AMBER	AMBER	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED
Normal Phase	AMBER	AMBER	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED
Normal Phase	AMBER	AMBER	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED	RED

Table B: Coordination Sequence (Secs)

Sequence	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table C: Schedule

Signal	Day of Week	Section
P 1	MON-FRI	ALL DAY
P 2	SAT-SUN	NA
P 3	MON-FRI	NA
P 4	SAT-SUN	NA

Table D: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table E: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table F: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table G: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table H: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table I: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table J: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table K: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table L: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table M: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table N: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table O: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table P: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table Q: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table R: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table S: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table T: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table U: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table V: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table W: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table X: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table Y: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table Z: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AA: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AB: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AC: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AD: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AE: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AF: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AG: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AH: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AI: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AJ: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AK: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AL: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AM: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AN: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AO: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AP: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AQ: Pre-Timed

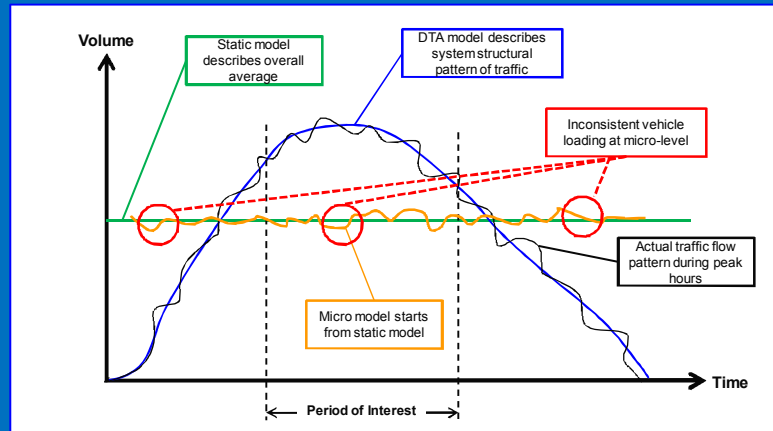
Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4	4	4

Table AR: Pre-Timed

Signal	Control	Control	Control	Control
1	4	4	4	4
2	4	4	4	4
3	4	4	4	4
4	4	4		

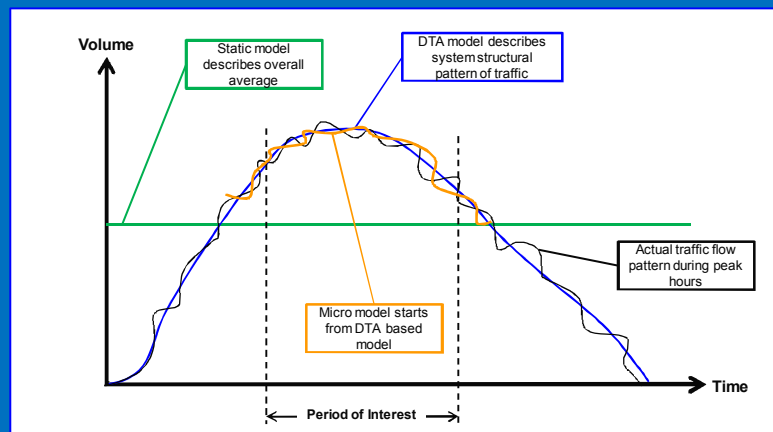
Challenges in Operational Planning

- Proper vehicle loading in future network conditions is critical



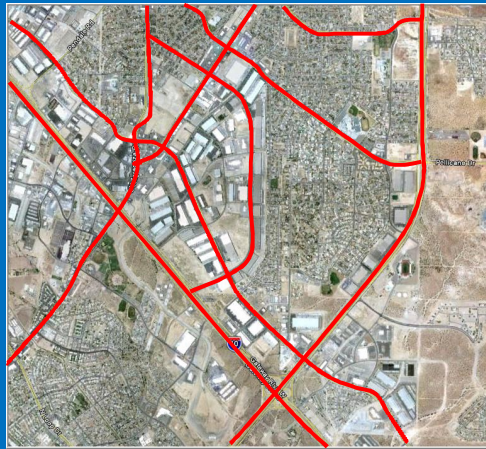
Challenges in Operational Planning

- Proper vehicle loading in future network conditions is critical

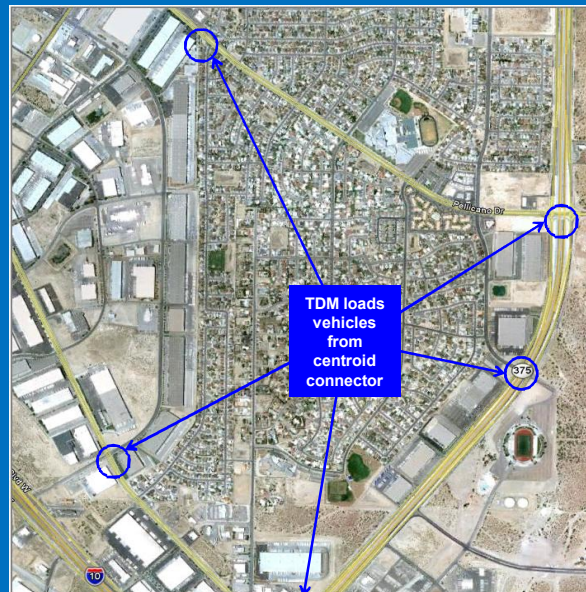


Challenges in Operational Planning

- Regional travel demand models usually do not represent the entire network – only major arterials.



Challenges in Operational Planning



Challenges in Operational Planning

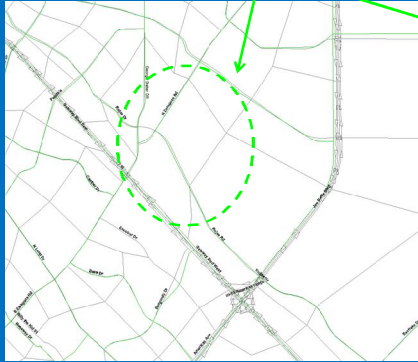


Challenges in Operational Planning

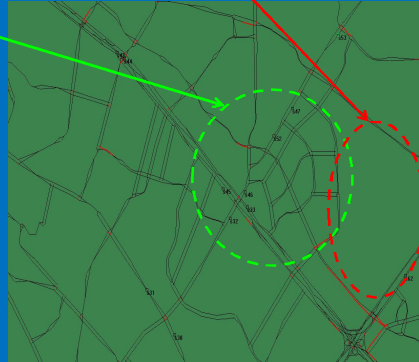
- How detailed is enough to give realistic results?
- How difficult is it to include smaller localized streets in regional models?

Challenges in Operational Planning

Additional links were added

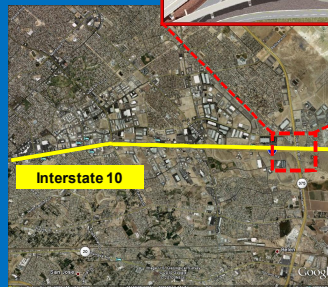
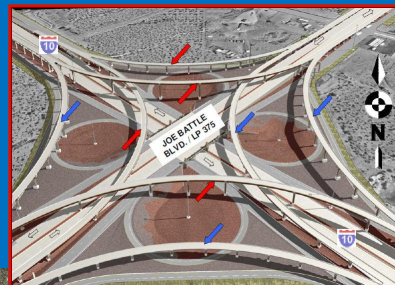


Street network still not detailed enough



Case Study I

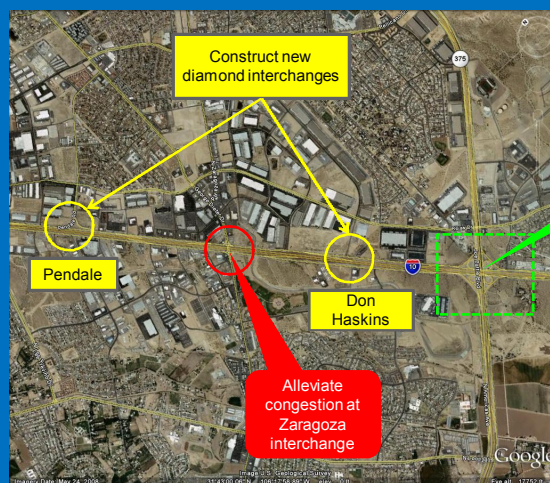
- TxDOT is constructing direct connectors at the I-10/Loop 375 interchange
- In addition, they want to construct two additional diamond interchanges west of interchange



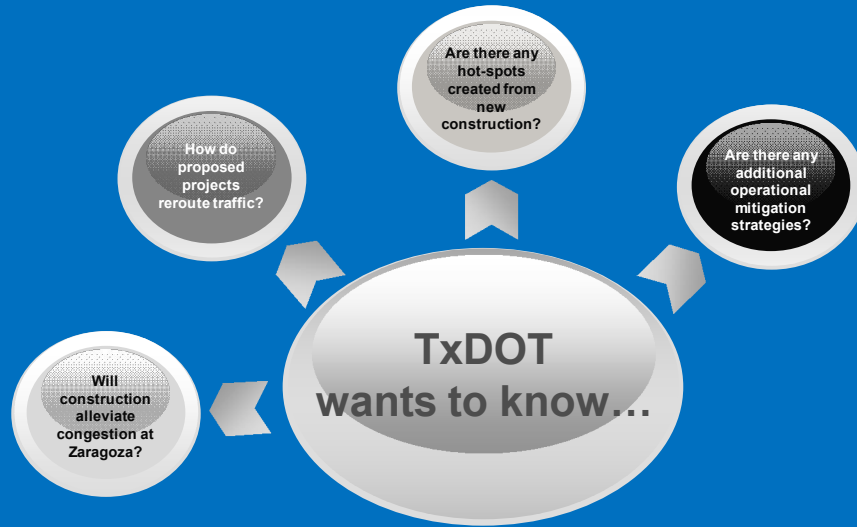
Case Study I

- TxDOT wants to reduce the severe congestion at the Zaragoza/I-10 diamond interchange
 - Propose two additional diamond interchanges up and downstream of Zaragoza
 - Reverse/braided ramps upstream of proposed interchanges
 - Possible diverging diamond interchange

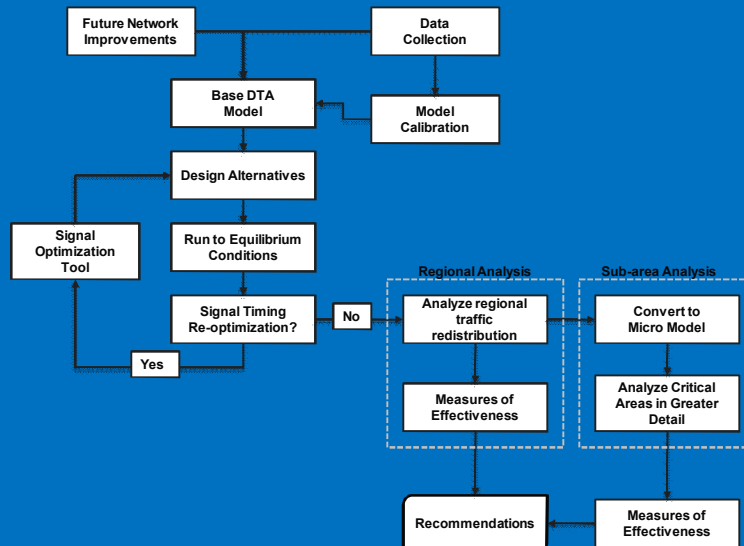
Case Study I



Case Study I



Case Study I

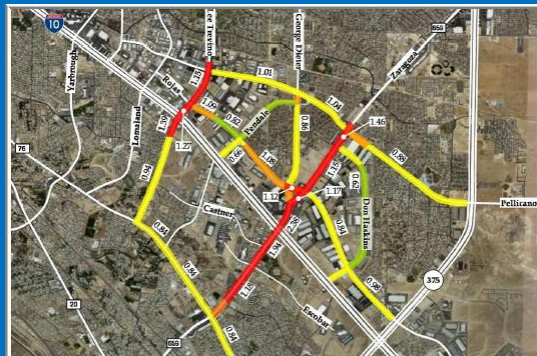


Case Study I

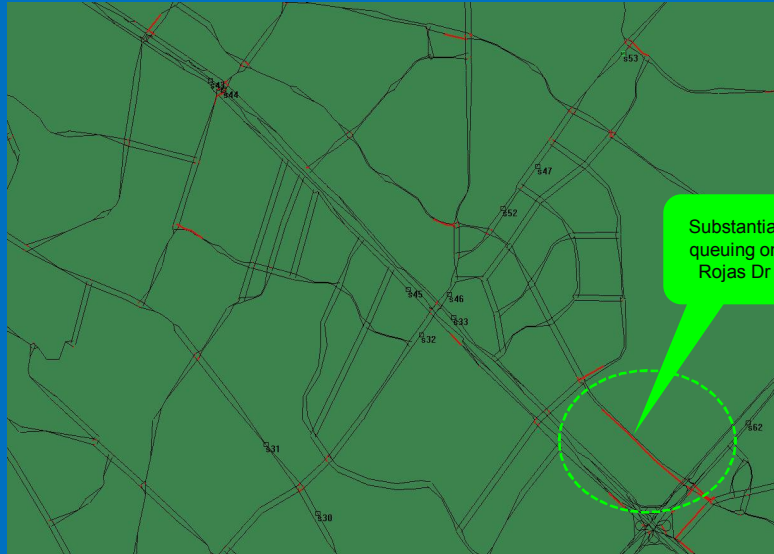
- Network loading and unloading of vehicles became a challenge.
 - Mesoscopic DTA model showed severe queuing westbound on Rojas Dr/Loop 375
 - Private consultant conducted independent study and came to same conclusion

“Rojas Dr will operate at a LOS E - F during peak periods of the day with substantial queuing”

Challenges in Operational Planning



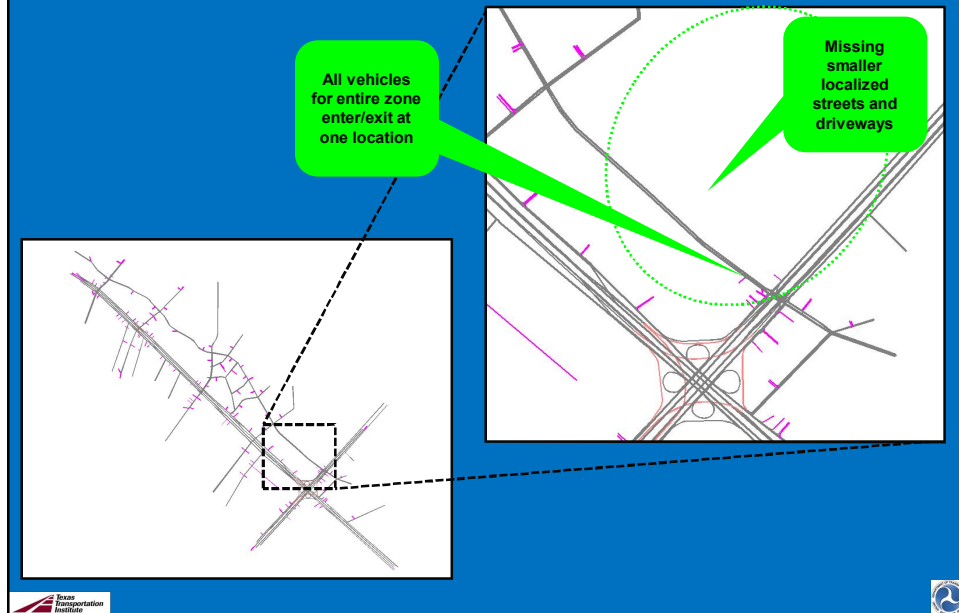
Case Study I



Case Study I

- Once we converted sub-area to micro-level, it was clear that the network was loading/unloading vehicles only in one specific spot on Rojas.

Case Study I



Case Study I

- Presented results to TxDOT and informed them of the limitations in using a regional model for operational planning projects
- TxDOT wants us to simulate the network again and include all smaller localized streets.

The more detailed the network, the more realistic the results will be

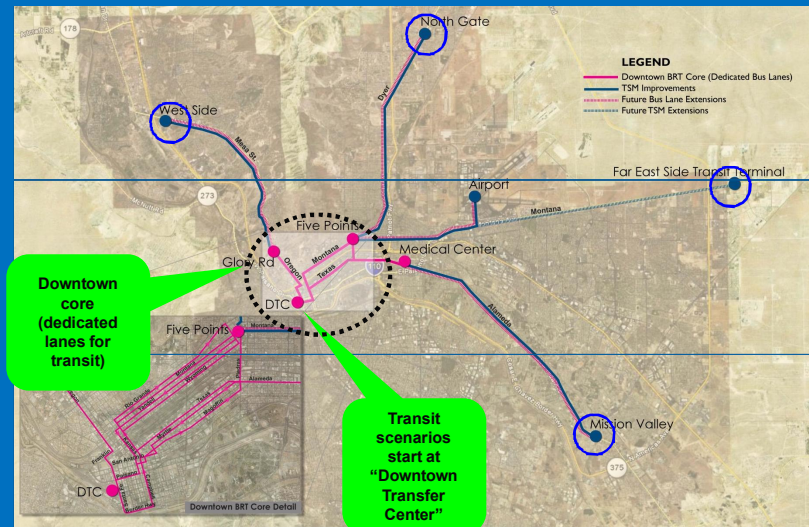
Case Study I



Case Study II

- The City of El Paso to conduct a transit corridor feasibility study
 - Adopt four alternative corridors
 - Different alternatives include
 - Bus Rapid Transit
 - Transit signal priority
 - Combination (BRT in core & signal priority on extensions)
 - What is the effect on traffic?

Case Study II



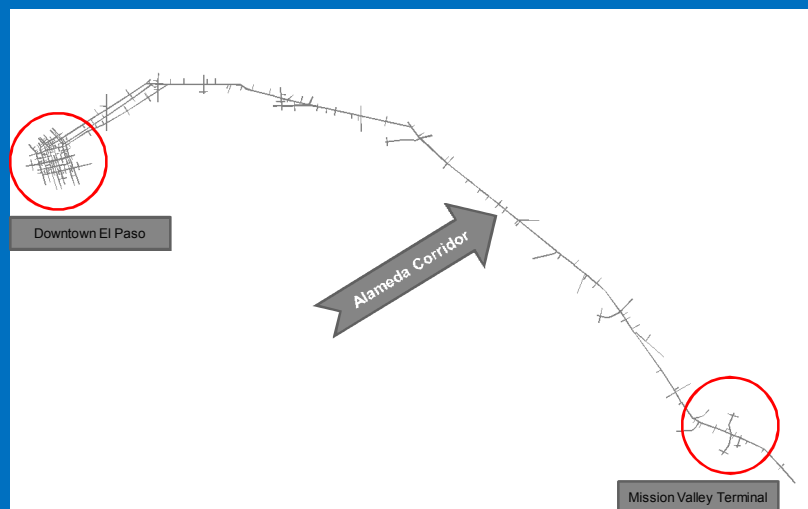
Case Study II

- Same methodology used as in case study I
 - Developed base year model
 - Run DTA model to equilibrium conditions
 - Extract sub-area and convert to micro-level
 - Run micro model with different transit management strategies

Case Study II

- Very large microscopic models
 - **Alameda corridor**
 - Over 10,800 links and connectors
 - 60 signals
 - 80,000 vehicles generated
 - Over 6,400 routes generated
 - Simulated for 4 hours
 - Paths updated every 15 minutes
 - All four transit corridors include all of downtown El Paso

Case Study II

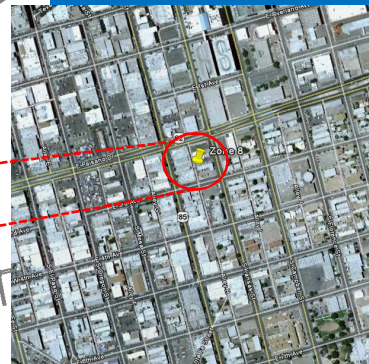
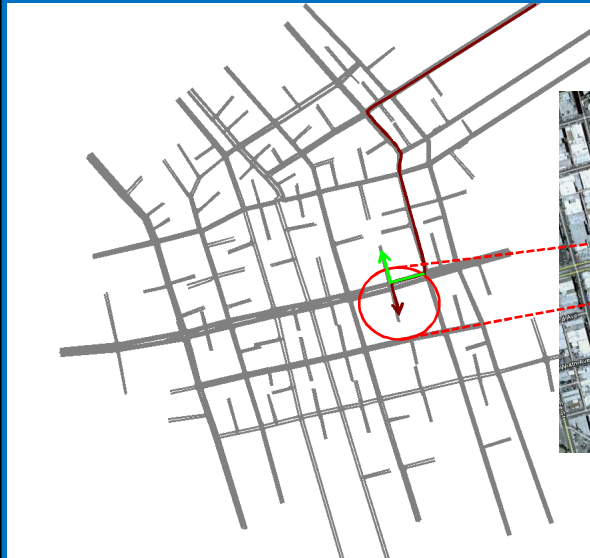


Case Study II

- Several weeks of calibration was needed for each model
- Downtown was difficult to calibrate due to size and number of zones
- Manual adjustment of vehicle destinations needed



Case Study II



Manually move some
routes to alternate
destination

Case Study II

- Simulation results were able to show impact of dedicated transit lane on traffic congestion
- Dedicated lane actually increased travel time for bus routes on Alameda
- Full BRT to extension terminals not feasible
- City has since reconsidered BRT and opted for BRT in core and signal priority to extensions

Recap

- Signal timing in future years needs to be optimized
- Care must be taken when translating vehicle loading between different levels of resolution
- Sufficient representation of roadway (links) in network
- Large micro-models require tremendous amount of calibration
- Sometimes using “best engineering judgment” is needed to further calibrate models.

Thank You!

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